# M-truncated soliton solutions of the fractional (4+1)-dimensional Fokas equation 

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#### Abstract

This article aims to examine M-truncated soliton solutions of the fractional $(4+1)$-dimensional Fokas equation (FE), which is a generalization of the Kadomtsev-Petviashvili (KP) and Davey-Stewartson (DS) equations. The fractional $(4+1)$-dimensional Fokas equation with the M-truncated derivative is also studied first time in this study. The generalized projective Riccati equations method (GPREM) is successfully implemented. In the application of the presented method, a suitable fractional wave transformation is chosen to convert the proposed model into a nonlinear ordinary differential equation. Then, a linear equation system is acquired utilizing the GPREM, the system is solved, and the suitable solution sets are obtained. Dark and singular soliton solutions are successfully derived. Under the selection of appropriate values of the parameters, 2D, 3D, and contour plots are also displayed for some solutions.


## 1. Introduction

A variety of real-life problems have been modeled using the nonlinear partial differential equations (NLPDEs) with integer or fractional order. Moreover, NLPDEs with integer or fractional order have main roles in area of quantum mechanics, fluid dynamics, nonlinear optics, plasma physics as well as biology, chemistry, and finance. Because of its wide application, investigation of the analytical and soliton solutions of the NLPDEs with integer or fractional order has been very popular among authors over the past few decades. Numerous techniques consisting of the analytical and numerical methods have been improved to gain the soliton and analytical solutions of the PDEs such as the combined improved Kudryashov-new extended auxiliary sub equation method [1], the enhanced modified extended tanh-expansion approach $[2,3]$, the sine-Gordon equation approach [4], F-expansion method [5], the tanh-coth function, the modified kudryashov expansion and rational sine-cosine approaches [6], the Riccati equation method [7],
the $\tan (\Theta / 2)$ expansion approach [8], the Jacobi elliptic functions methodology [9], the generalized Bernoulli sub-ODE scheme [10], the extended $\left(\frac{G^{\prime}}{G^{2}}\right)$-expansion scheme 11 , Nucci's reduction method [12], the new Kudryashov method 13 15], the sub-equation method based on Riccati equation [16], and the modified Sardar subequation method (17.
Fractional differential equations have been utilized the modeling many phenomena in a variety of branches of engineering and science [18,19]. Thus, various and substantial definitions of fractional derivatives types have been enhanced in the literature such as: Grunwald- Letnikov, Rie-mann-Liouville, Caputo 20], Caputo-Fabrizio [21], Atangana-Baleanu [22, 23], the conformable fractional derivative [24], and the M-truncated derivative 11].
The $(4+1)$-dimensional Fokas equation is expressed by the following structure [25]:
$4 \vartheta_{t x}-\vartheta_{x x x y}+\vartheta_{x y y y}+12 \vartheta_{x} \vartheta_{y}+12 \vartheta \vartheta_{x y}-6 \vartheta_{z s}=0$, (1) in which $\vartheta(x, y, z, s, t)$. The model was firstly presented by A. S. Fokas 25 and the FE
is the extension form of Davey-Stewartson and Kadomtsev-Petviashvili equations to some higher-dimensional nonlinear wave equations [25]. So, the $(4+1)$-dimensional FE is taken into account as a higher dimensional integrable model in mathematical physics. The $(4+1)$-dimensional FE models the finite-amplitude wave packet in fluid dynamics.
Up to now, soliton and analytical solutions of the FE have been investigated by utilizing various significant approaches. In [26], Yinghui He discussed the analytical solutions using the extended Fexpansion scheme. Hirota's bilinear methodology was used to examine the FE in 27. Kim and Sakthival obtained some traveling wave solutions of the ( $4+1$ )-dimensional FE by applying the $\left(\frac{G^{\prime}}{G}\right)$ expansion scheme in [28]. In [29], the Sardar subequation scheme and new extended hyperbolic function approach were utilized to build the soliton solutions of the ( $4+1$ )-dimensional fractionalorder FE. Bo and Sheng used the generalized Fexpansion method to construct some exact solutions with arbitrary functions in [30]. Wazwaz implemented the simplified Hirota's approach to gain a variety of soliton solutions of the presented model in [31]. In [32], the (4+1)-dimensional FE was studied using the modified simple equation and the extended simplest equation schemes by Al-Amr and El-Ganaini. Baskonus et.al. constructed various soliton solutions by performing sine-Gordon expansion method in 33 .

In this paper, we intend to achieve the soliton solutions of the space-time fractional $(4+1)$ dimensional FE involving M-truncated derivative in the form:

$$
\begin{array}{r}
4 D_{M, t}^{\alpha, \gamma} D_{M, x}^{\alpha, \gamma} \vartheta-D_{M, x}^{3 \alpha, \gamma} D_{M, y}^{\alpha, \gamma} \vartheta+D_{M, x}^{\alpha, \gamma} D_{M, y}^{3 \alpha, \gamma} \vartheta \\
+12 D_{M, x}^{\alpha, \gamma} \vartheta D_{M, y}^{\alpha, \gamma} \vartheta+12 \vartheta D_{M, x}^{\alpha, \gamma} D_{M, y}^{\alpha, \gamma} \vartheta  \tag{2}\\
-6 D_{M, z}^{\alpha, \gamma} D_{M, s}^{\alpha, \gamma} \vartheta=0 .
\end{array}
$$

Herein, $\quad D_{M, x}^{\alpha, \gamma} \vartheta(x, y, z, s, t)$ represents the Mtruncated derivative of $\vartheta$ with respect to $x, 0<$ $\alpha \leq 1$. The space-time fractional form including the M-truncated derivative of $(4+1)$-dimensional FE has been examined utilizing the GPREM for the first time in this study.

The remain of this study is arranged as follows: The definition and properties of the M-truncated derivative are expressed in section 2. Mathematical analysis of the presented model is offered in section 3 . We also submit the description and enforcement of GPREM in section 4. To observe the physical explanations of the derived results, we present the graphical potraits in section 5 . Finally, we give the conclusion in the last section.

## 2. The M-truncated derivative

Definition 1. The truncated Mittag-Leffler function [11] is identified as:

$$
{ }_{i} E_{\gamma}(c)=\sum_{m=0}^{i} \frac{c^{m}}{\Gamma(m \gamma+1)},
$$

for $\gamma>0$, and $c \in \mathrm{C}$.
Definition 2. Presume that $\delta:[0, \infty) \rightarrow \mathrm{R}$, the $M$-truncated derivative of $\delta$ with order $\alpha$ is defined by (11]

$$
D_{M}^{\alpha, \gamma}(\delta(x))=\lim _{\varepsilon \rightarrow 0} \frac{\delta\left(x_{i} E_{\gamma}\left(\varepsilon x^{-\alpha}\right)\right)-\delta(x)}{\varepsilon}
$$

where $x>0$ and $\alpha \in(0,1)$.
Theorem 1. Consider if $0<\alpha \leq 1, \gamma>0$ and considering $\delta(t)$ and $\theta(t)$ are differentiable of $\alpha^{\prime} s$ order at $x>0$, then
(1) $D_{M}^{\alpha, \gamma}(a \delta(x)+b \theta(x))=a D_{M}^{\alpha, \gamma}(\delta(x))+$ $b D_{M}^{\alpha, \gamma}(\theta(x))$, for all $a, b \in \mathrm{R}$,
(2) $D_{M}^{\alpha, \gamma}(\delta(x) \theta(x))=\theta(x) D_{M}^{\alpha, \beta}(\delta(x))+$ $\delta(x) D_{M}^{\alpha, \gamma}(\theta(x))$,
(3) $D_{M}^{\alpha, \gamma}\left(\frac{\delta(x)}{\theta(x)}\right)=\frac{\theta(x) D_{M}^{\alpha, \gamma}(\delta(x))-\delta(x) D_{M}^{\alpha, \gamma}(\theta(x))}{\theta^{2}(x)}$,
(4) $D_{M}^{\alpha, \gamma} \delta(x)=\frac{x^{1-\alpha}}{\Gamma(\gamma+1)} \frac{d \delta}{d x}$.

The truncated M-fractional derivative is an extension structure of the conformable fractional derivative.

## 3. Nonlinear ordinary differential form of the fractional $(4+1)$-dimensional FE

In order to gain the NODE form of Eq. (2), we should firstly determine wave transformation with M-truncated derivative as follows:

$$
\begin{gather*}
\vartheta(x, y, z, s, t)=V(\zeta) \\
\zeta=\frac{\Gamma(1+\gamma)\left(\rho_{1} x^{\alpha}+\rho_{2} y^{\alpha}+\rho_{3} z^{\alpha}+\rho_{4} s^{\alpha}+\rho_{5} t^{\alpha}\right)}{\alpha} . \tag{3}
\end{gather*}
$$

Herein, $\rho_{1}, \rho_{2}, \rho_{3}, \rho_{4}$ and $\rho_{5}$ are nonzero real numbers. Using the wave transformation in Eq.(3), Eq. (2) transform into the following NODE:

$$
\begin{align*}
\left(\rho_{1} \rho_{2}^{3}-\rho_{1}^{3} \rho_{2}\right) V^{(i v)} & +\left(4 \rho_{1} \rho_{5}-6 \rho_{3} \rho_{4}\right) V^{\prime \prime} \\
& +12 \rho_{1} \rho_{2}\left(V V^{\prime}\right)^{\prime}=0 \tag{4}
\end{align*}
$$

Integrating Eq. (4) twice with respect to $\zeta$ and presuming the integration constants to zero, we achieve the following equation:

$$
\begin{array}{r}
\left(\rho_{1} \rho_{2}^{3}-\rho_{1}^{3} \rho_{2}\right) V^{\prime \prime}+\left(4 \rho_{1} \rho_{5}-6 \rho_{3} \rho_{4}\right) V \\
+12 \rho_{1} \rho_{2} V^{2}=0 \tag{5}
\end{array}
$$

## 4. A brief sketch of the GPREM and its application

### 4.1. Outline of the GPREM

According to the GPREM [14], the solution of the Eq.(5) has the following structure:

$$
\begin{equation*}
V(\zeta)=A_{0}+\sum_{k=1}^{M} \kappa^{k-1}(\zeta)\left[A_{k} \kappa(\zeta)+B_{k} \sigma(\zeta)\right], \tag{6}
\end{equation*}
$$

in which $A_{0}, A_{k}$ and $B_{k}(1,2, \ldots, M)$ are real contants to be computed, $M$ is the balance number, and $\kappa(\zeta)$ and $\sigma(\zeta)$ satisfy the following equations:

$$
\begin{gather*}
\kappa^{\prime}(\zeta)=\varepsilon \kappa(\zeta) \sigma(\zeta),  \tag{7}\\
\sigma^{\prime}(\zeta)=\lambda+\varepsilon \sigma^{2}(\zeta)-\chi \kappa(\zeta), \quad \varepsilon=\mp 1, \tag{8}
\end{gather*}
$$

in which

$$
\begin{equation*}
\sigma^{2}(\zeta)=-\varepsilon\left(\lambda-2 \chi \kappa(\zeta)+\frac{\chi^{2}+c}{\lambda} \kappa^{2}(\zeta)\right), \tag{9}
\end{equation*}
$$

$c=\mp 1, \lambda$ and $\chi$ are nonzero real constants. Assuming as $\lambda=\chi=0$, Eq.(5) has the following solution structure:

$$
\begin{equation*}
V(\zeta)=\sum_{k=1}^{M} A_{k} \sigma^{k}(\zeta), \tag{10}
\end{equation*}
$$

in which $\sigma(\zeta)$ satisfies the following relation:

$$
\begin{equation*}
\sigma^{\prime}(\zeta)=\sigma^{2}(\zeta) \tag{11}
\end{equation*}
$$

Utilizing the Eqs.(7) and (8), the following solution functions are gained:
Case 1: If $\varepsilon=-1, c=-1$ and $\lambda>0$, we get,

$$
\begin{align*}
\kappa_{1}(\zeta) & =\frac{\lambda \operatorname{sech}(\sqrt{\lambda} \zeta)}{\chi \operatorname{sech}(\sqrt{\lambda} \zeta)+1}, \\
\sigma_{1}(\zeta) & =\frac{\sqrt{\lambda} \tanh (\sqrt{\lambda} \zeta)}{\chi \operatorname{sech}(\sqrt{\lambda} \zeta)+1} . \tag{12}
\end{align*}
$$

Case 2: If $\varepsilon=-1, c=1$ and $\lambda>0$, we get,

$$
\begin{align*}
& \kappa_{2}(\zeta)=\frac{\lambda \operatorname{csch}(\sqrt{\lambda} \zeta)}{\chi \operatorname{csch}(\sqrt{\lambda} \zeta)+1}, \\
& \sigma_{2}(\zeta)=\frac{\sqrt{\lambda} \operatorname{coth}(\sqrt{\lambda} \zeta)}{\chi \operatorname{csch}(\sqrt{\lambda} \zeta)+1} . \tag{13}
\end{align*}
$$

Case 3: If $\varepsilon=1, c=-1$ and $\lambda>0$, we get,

$$
\begin{array}{ll}
\kappa_{3}(\zeta)=\frac{\lambda \sec (\sqrt{\lambda} \zeta)}{\chi \sec (\sqrt{\lambda} \zeta)+1}, & \sigma_{3}(\zeta)=\frac{\sqrt{\lambda} \tan (\sqrt{\lambda} \zeta)}{\chi \sec (\sqrt{\lambda} \zeta)+1}, \\
\kappa_{4}(\zeta)=\frac{\lambda \csc (\sqrt{\lambda} \zeta)}{\chi \csc (\sqrt{\lambda} \zeta)+1}, & \sigma_{4}(\zeta)=-\frac{\sqrt{\lambda} \cot (\sqrt{\lambda} \zeta)}{\chi \csc (\sqrt{\lambda} \zeta)+1} . \tag{14}
\end{array}
$$

Case 4: If $\lambda=\chi=0$,

$$
\begin{equation*}
\kappa_{5}(\zeta)=\frac{C}{\zeta}, \sigma_{5}(\zeta)=\frac{1}{\varepsilon \zeta} . \tag{15}
\end{equation*}
$$

Herein, $C$ is a nonzero constant. Insert Eq. (6) and its derivatives to Eq. (5) and taking into account Eqs. (7)-(9), we acquire a polynomial consisting of $\kappa^{k}(\zeta) \sigma^{l}(\zeta),(k, l=0,1.2 .3, \ldots, M)$. If we collect the coefficients of $\kappa^{k}(\zeta) \sigma^{l}(\zeta)$ involving the same power and equal each coefficient to zero,
we gain a system of algebraic equations which consist of $A_{0}, A_{k}, B_{k}, \chi, \lambda, \rho_{1}, \rho_{2}, \rho_{3}, \rho_{4}$, and $\rho_{5}$. Solving this system, then inserting these parameter values into Eq. (5), afterwards utilizing the solutions Eqs. (12)-(15) and Eq. (3), we achieve the solutions to Eq. (22).

### 4.2. Implementation of GPREM to the fractional (4+1)-dimensional FE

Considering Eq. (5) and applying the balance rule, we get $M=2$. Eq. (6) is rewritten in the following structure:

$$
\begin{equation*}
V(\zeta)=A_{0}+A_{1} \kappa(\zeta)+B_{1} \sigma(\zeta)+A_{2} \kappa(\zeta)+B_{2} \sigma(\zeta), \tag{16}
\end{equation*}
$$

in which $A_{0}, A_{1}, A_{2}, B_{1}$, and $B_{2}$ are constants. Inserting Eq. (16) into Eq.(5) taking into account Eqs. (7)-(9), we get a system of algebraic equations. Considering the coefficients of $\kappa^{k}(\zeta) \sigma^{l}(\zeta)$ as zero, then solving the system, we derive the solution functions as:
Case 1: If $\varepsilon=-1, c=-1$ and $\lambda>0$, we get the following results:
Result ${ }_{1}$ :


## Result $_{2}$ :


and subsequently, we get the following solution functions:

$$
\begin{align*}
& \vartheta_{1,1}(x, y, z, s, t)=\left(\frac{\left(3 \chi \rho_{3} \rho_{4}-2 \chi \rho_{1} \rho_{5}\right) \cosh (\sqrt{\lambda} \zeta)}{2 \rho_{1} \rho_{2}(\chi+\cosh (\sqrt{\lambda} \zeta))}\right) \\
& -\left(\frac{\sqrt{\lambda} \omega_{1} \sinh \left(\frac{1}{\alpha}(\sqrt{\lambda} \zeta)\right)-3 \rho_{3} \rho_{4}+2 \rho_{1} \rho_{5}}{2 \rho_{1} \rho_{2}(\chi+\cosh (\sqrt{\lambda} \zeta))^{2}}\right),  \tag{19}\\
& \vartheta_{1,2}(x, y, z, s, t)=\left(\frac{\left(3 \chi \rho_{3} \rho_{4}-2 \chi \rho_{1} \rho_{5}\right) \cosh (\sqrt{\lambda} \zeta)}{2 \rho_{1} \rho_{2}(\chi+\cosh (\sqrt{\lambda} \zeta))}\right) \\
& +\left(\frac{\sqrt{\lambda} \omega_{1} \sinh \left(\frac{1}{\alpha}(\sqrt{\lambda} \zeta)\right)+3 \rho_{3} \rho_{4}-2 \rho_{1} \rho_{5}}{2 \rho_{1} \rho_{2}(\chi+(\cosh (\sqrt{2} \lambda \zeta)))^{2}}\right), \tag{20}
\end{align*}
$$

in which
$\omega_{1}=\sqrt{\rho_{1} \rho_{2}\left(\rho_{1}{ }^{2}-\rho_{2}^{2}\right)\left(\chi^{2}-1\right) \frac{\left(2 \rho_{1} \rho_{5}-3 \rho_{3} \rho_{4}\right)}{2}}$
and
$\zeta=\frac{\Gamma(1+\gamma)\left(\rho_{1} x^{\alpha}+\rho_{2} y^{\alpha}+\rho_{3} z^{\alpha}+\rho_{4} s^{\alpha}+\rho_{5} t^{\alpha}\right)}{\alpha}$.
Case 2: If $\varepsilon=-1, c=1$ and $\lambda>0$,we get the following results:

## Result $_{3}$ :

## Result ${ }_{4}$ :

$$
\left\{\begin{array}{l}
\lambda=\frac{2\left(2 \rho_{1} \rho_{5}-3 \rho_{3} \rho_{4}\right)}{\left(\rho_{1}^{2}-\rho_{2}{ }^{2}\right) \rho_{1} \rho_{2}}, A_{0}=0, A_{1}=-\frac{1}{4} \chi\left(\rho_{1}^{2}-\rho_{2}^{2}\right)  \tag{22}\\
A_{2}=\frac{\left(\rho_{1}-\rho_{2}\right)^{2}\left(\rho_{1}+\rho_{2}\right)^{2}\left(\chi^{2}+1\right) \rho_{1} \rho_{2}}{16 \rho_{1} \rho_{5}-24 \rho_{3} \rho_{4}}, B_{1}=0, \\
B_{2}=\frac{\left(\rho_{1}^{2}-\rho_{2}^{2}\right) \sqrt{2} \sqrt{\left(2 \rho_{1} \rho_{5}-3 \rho_{3} \rho_{4}\right)\left(\rho_{1}^{2}-\rho_{2}^{2}\right)\left(\chi^{2}+1\right) \rho_{1} \rho_{2}}}{16 \rho_{1} \rho_{5}-24 \rho_{3} \rho_{4}}
\end{array}\right\}
$$

and subsequently, we get the following solution functions:

$$
\begin{align*}
& \vartheta_{2,1}(x, y, z, s, t)=\left(\frac{-\sqrt{\lambda} \omega_{2} \cosh (\sqrt{\lambda} \zeta)+\left(3 \rho_{3} \rho_{4}-2 \rho_{1} \rho_{5}\right)(\chi \sinh (\sqrt{\lambda} \zeta)-1)}{2 \rho_{1} \rho_{2}\left((\cosh (\sqrt{\lambda} \zeta))^{2}+\chi^{2}+2 \chi \sinh (\sqrt{\lambda} \zeta)-1\right)}\right)  \tag{23}\\
& \vartheta_{2,2}(x, y, z, s, t)=\left(\frac{\sqrt{\lambda} \omega_{2} \cosh (\sqrt{\lambda} \zeta)+\left(3 \rho_{3} \rho_{4}-2 \rho_{1} \rho_{5}\right)(\chi \sinh (\sqrt{\lambda} \zeta)-1)}{2 \rho_{1} \rho_{2}\left((\cosh (\sqrt{\lambda} \zeta))^{2}+\chi^{2}+2 \chi \sinh (\sqrt{\lambda} \zeta)-1\right)}\right) \tag{24}
\end{align*}
$$

in which

$$
\omega_{2}=-\sqrt{\rho_{1} \rho_{2}\left(\rho_{1}^{2}-\rho_{2}^{2}\right)\left(\chi^{2}+1\right) \frac{\left(2 \rho_{1} \rho_{5}-3 \rho_{3} \rho_{4}\right)}{2}}
$$

and

$$
\zeta=\frac{\Gamma(1+\gamma)\left(\rho_{1} x^{\alpha}+\rho_{2} y^{\alpha}+\rho_{3} z^{\alpha}+\rho_{4} s^{\alpha}+\rho_{5} t^{\alpha}\right)}{\alpha}
$$

Case 3: If $\varepsilon=1, c=-1$ and $\lambda>0$, we get the following results:

## Result ${ }_{5}$ :

$$
\begin{align*}
& \lambda=\frac{2\left(2 \rho_{1} \rho_{5}-3 \rho_{3} \rho_{4}\right)}{\left(\rho_{1}^{2}-\rho_{2}{ }^{2}\right) \rho_{1} \rho_{2}}, A_{0}=-\frac{\left(2 \rho_{1} \rho_{5}-3 \rho_{3} \rho_{4}\right)}{6 \rho_{1} \rho_{2}}, \\
& \left\{\begin{array}{l}
A_{1}=\frac{1}{4} \chi\left(\rho_{1}^{2}-\rho_{2}{ }^{2}\right), \\
A_{2}=-\frac{\left(\rho_{1}-\rho_{2}\right)^{2}\left(\rho_{1}+\rho_{2}\right)^{2}\left(\chi^{2}-1\right) \rho_{1} \rho_{2}}{16 \rho_{1} \rho_{5}-24 \rho_{3} \rho_{4}}, B_{1}=0, \\
B_{2}=-\frac{\left(\rho_{1}^{2}-\rho_{2}^{2}\right) \sqrt{2} \sqrt{-\left(2 \rho_{1} \rho_{5}-3 \rho_{3} \rho_{4}\right)\left(\rho_{1}^{2}-\rho_{2}{ }^{2}\right)\left(\chi^{2}-1\right) \rho_{1} \rho_{2}}}{16 \rho_{1} \rho_{5}-24 \rho_{3} \rho_{4}}
\end{array}\right.
\end{align*}
$$

## Result ${ }_{6}$ :

$$
\begin{align*}
& \lambda=\frac{2\left(2 \rho_{1} \rho_{5}-3 \rho_{3} \rho_{4}\right)}{\left(\rho_{1}^{2}-\rho_{2}{ }^{2}\right) \rho_{1} \rho_{2}}, A_{0}=-\frac{\left(2 \rho_{1} \rho_{5}-3 \rho_{3} \rho_{4}\right)}{6 \rho_{1} \rho_{2}}, \\
& \left\{\begin{array}{l}
A_{1}=\frac{1}{4} \chi\left(\rho_{1}^{2}-\rho_{2}^{2}\right), \\
A_{2}=-\frac{\left(\rho_{1}-\rho_{2}\right)^{2}\left(\rho_{1}+\rho_{2}\right)^{2}\left(\chi^{2}-1\right) \rho_{1} \rho_{2}}{16 \rho_{1} \rho_{5}-24 \rho_{3} \rho_{4}}, B_{1}=0 \\
B_{2}=\frac{\left(\rho_{1}{ }^{2}-\rho_{2}^{2}\right) \sqrt{2} \sqrt{-\left(2 \rho_{1} \rho_{5}-3 \rho_{3} \rho_{4}\right)\left(\rho_{1}{ }^{2}-\rho_{2}{ }^{2}\right)\left(\chi^{2}-1\right) \rho_{1} \rho_{2}}}{16 \rho_{1} \rho_{5}-24 \rho_{3} \rho_{4}}
\end{array}\right.
\end{align*}
$$

and subsequently, we get the following solution function

$$
\begin{align*}
& \vartheta_{3,1}(x, y, z, s, t)=\left(\frac{3 \sqrt{\lambda} \sqrt{-\omega_{1}} \sin (\sqrt{\lambda} \zeta)}{6 \rho_{1} \rho_{2}(\chi+\cos (\sqrt{\lambda} \zeta))^{2}}\right) \\
& +\left(\frac{\left((\cos (\sqrt{\lambda} \zeta))^{2}-\chi \cos (\sqrt{\lambda} \zeta)+\chi^{2}-3\right)\left(3 \rho_{3} \rho_{4}-2 \rho_{1} \rho_{5}\right)}{6 \rho_{1} \rho_{2}(\chi+\cos (\sqrt{\lambda} \zeta))^{2}}\right),  \tag{27}\\
& \vartheta_{3,2}(x, y, z, s, t)=\left(\frac{-3 \sqrt{\lambda} \sqrt{-\omega_{1}} \sin (\sqrt{\lambda} \zeta)}{6 \rho_{1} \rho_{2}(\chi+\cos (\sqrt{\lambda} \zeta))^{2}}\right) \\
& +\left(\frac{\left((\cos (\sqrt{\lambda} \zeta))^{2}-\chi \cos (\sqrt{\lambda} \zeta)+\chi^{2}-3\right)\left(3 \rho_{3} \rho_{4}-2 \rho_{1} \rho_{5}\right)}{6 \rho_{1} \rho_{2}(\chi+\cos (\sqrt{\lambda} \zeta))^{2}}\right),  \tag{28}\\
& \vartheta_{4,1}(x, y, z, s, t)=\left(\frac{3 \sqrt{\lambda} \sqrt{-\omega_{1}} \cos (\sqrt{\lambda} \zeta)}{6 \rho_{1} \rho_{2}(\chi+\cos (\sqrt{\lambda} \zeta))^{2}}\right) \\
& +\left(\frac{\left((\cos (\sqrt{\lambda} \zeta))^{2}+\chi \sin (\sqrt{\lambda} \zeta)-\chi^{2}+2\right)\left(3 \rho_{3} \rho_{4}-2 \rho_{1} \rho_{5}\right)}{6 \rho_{1} \rho_{2}\left(2 \chi \sin (\sqrt{\lambda} \zeta)-2(\cos (\sqrt{\lambda} \zeta))^{2}+\chi^{2}+1\right)}\right), \tag{29}
\end{align*}
$$

$$
\begin{align*}
& \vartheta_{4,2}(x, y, z, s, t)=\left(\frac{-3 \sqrt{\lambda} \sqrt{-\omega_{1}} \cos (\sqrt{\lambda} \zeta)}{6 \rho_{1} \rho_{2}(\chi+\cos (\sqrt{\lambda} \zeta))^{2}}\right) \\
& +\left(\frac{\left((\cos (\sqrt{\lambda} \zeta))^{2}+\chi \sin (\sqrt{\lambda} \zeta)-\chi^{2}+2\right)\left(3 \rho_{3} \rho_{4}-2 \rho_{1} \rho_{5}\right)}{6 \rho_{1} \rho_{2}\left(2 \chi \sin (\sqrt{\lambda} \zeta)-2(\cos (\sqrt{\lambda} \zeta))^{2}+\chi^{2}+1\right)}\right) \tag{30}
\end{align*}
$$

in which

$$
\omega_{1}=\sqrt{\rho_{1} \rho_{2}\left(\rho_{1}^{2}-\rho_{2}^{2}\right)\left(\chi^{2}-1\right) \frac{\left(2 \rho_{1} \rho_{5}-3 \rho_{3} \rho_{4}\right)}{2}}
$$

and $\zeta=\frac{\Gamma(1+\gamma)\left(\rho_{1} x^{\alpha}+\rho_{2} y^{\alpha}+\rho_{3} z^{\alpha}+\rho_{4} s^{\alpha}+\rho_{5} t^{\alpha}\right)}{\alpha}$.

## 5. Results and discussion

In this section, we present some graphical portraits and physical interpretations of the resulted solutions. For appropriate variables of unknown parameters, we depict various graphs with $3 \mathrm{D}, 2 \mathrm{D}$ and contour plots. We get the dark and singular soliton solutions for the model. Figs. 1.2 show some of the obtained solutions. We display 3D and contour graphs of $\vartheta_{1,1}(x, y, z, s, t)$ in Eq. 19 for the parameters $\rho_{1}=3, \rho_{2}=-1$, $\rho_{3}=2, \rho_{4}=1, \rho_{5}=-2, \gamma=0.5, \mathrm{y}=1, \mathrm{z}=1$,
$s=1, \chi=5$, and $\alpha=0.8$. Fig 1 (a) and fig 1 (b) show the dark soliton. Fig. 1f(c) also demonstrates 2D soliton profile for $t=5,7,9$. It can be seen that the amplitude and the shape of the dark soliton remain same. Moreover, as t increases, soliton goes to the right. Fig. 1 (d) is the 2D graphical portrait to demonstrate the effect of the $\alpha$ when $\alpha$ takes the values as $0.7,0.8,0.9$ and 1.0 , respectively. Soliton keeps its dark soliton view but if we pay attention to the peaks of the soliton, as if soliton moves to the right. Thus, we can say that this situation is not the various structures of the soliton resting on the fractional orders.
Fig 2 (a) and Fig 2 (b) are 3D and contour graphs of $\vartheta_{2,1}(x, y, z, s, t)$ given in Eq. 23 and these graphs demonstrate the singular soliton for the parameters $\quad \rho_{1}=3, \rho_{2}=-1, \rho_{3}=3, \rho_{4}=1, \rho_{5}=-3, \gamma=0.5$, $y=1, z=1, \mathrm{~s}=1, \chi=-5$, and $\alpha=1$. Fig. 2-(c) also demonstrates 2 D soliton profile for $t=3,5,7$. It can be seen that the shape of the singular soliton remains the same. Moreover, while $t$ decrases, soliton moves to the left. Fig. 2 (d) is the 2D graphical portrait to demonstrate the


Figure 1. The dark soliton portraits of $\vartheta_{1,1}(x, 1,1,1, t)$ in Eq. 19 for the parameters $\rho_{1}=3, \rho_{2}=-1, \rho_{3}=3, \rho_{4}=2, \rho_{5}=-3, \gamma=0.5, y=1, z=1, \mathrm{~s}=1, \chi=5$, and $\alpha=0.8$.


Figure 2. The singular soliton portraits of $\vartheta_{2,1}(x, 1,1,1, t)$ in Eq. 23) for the parameters $\rho_{1}=3, \rho_{2}=-1, \rho_{3}=3, \rho_{4}=2, \rho_{5}=-3, \gamma=0.5, y=1, z=1, s=1, \chi=-5$, and $\alpha=1$.
effect of the $\alpha$ when $\alpha$ takes the values as $0.8,0.85,0.9$ and 1.0 , respectively. Thus, we can say that this situation is not the different structures of the soliton resting on the fractional orders.

## 6. Conclusion

In this study, for the first time, the generalized projective Riccati equations method was efficaciously employed to scrutinize analytical solutions for the fractional $(4+1)$ dimensional Fokas equation with M-truncated derivative. Some analytical solutions and singular and dark soliton solutions are acquired. 3D, contour, and 2D graphs were added to exhibit the physical illustrations of some resulted solutions. The GPREM can be successfully implemented to the different fractional forms of $(4+1)$-dimensional Fokas equation. Hence, the results show that the GPREM is a very effectual and profitable tool for solving such higher order NLPDEs occurring in region associated with physics, chemical, biology, and mathematics along with engineering.

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